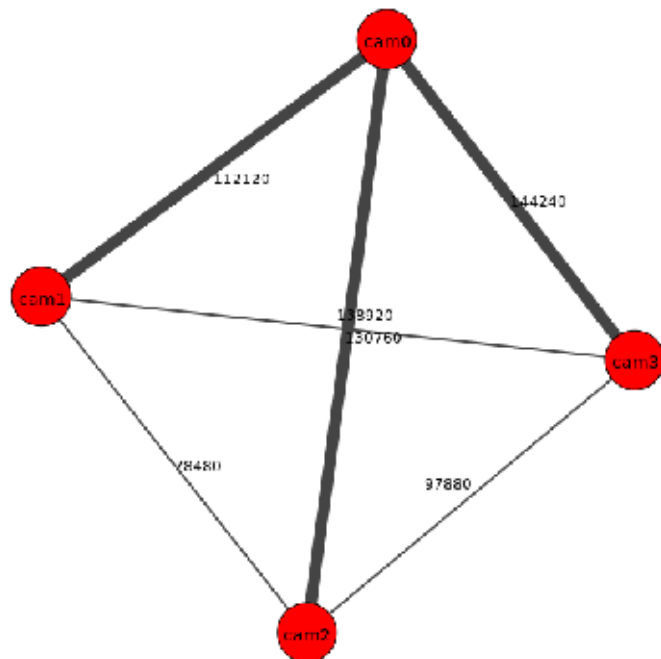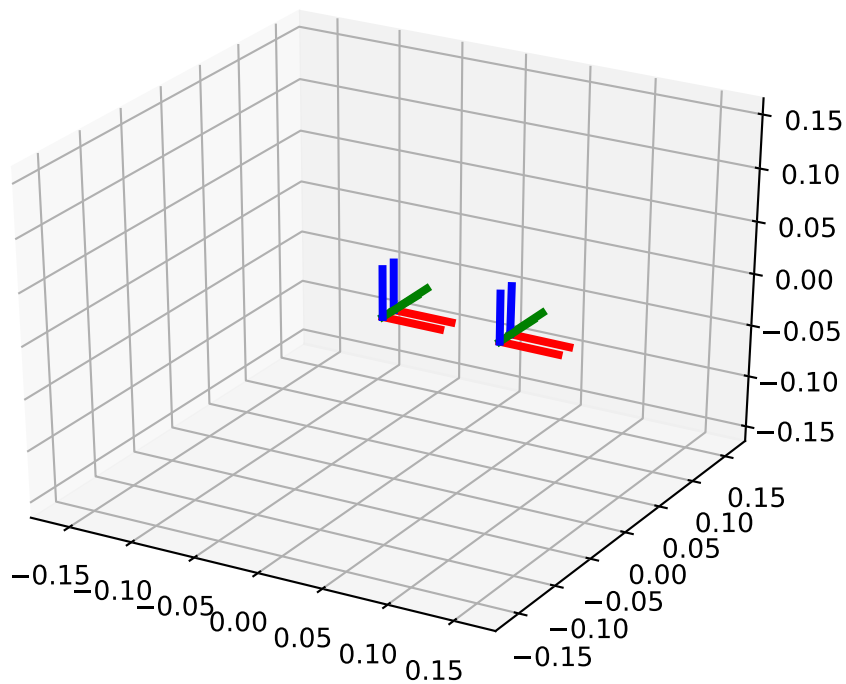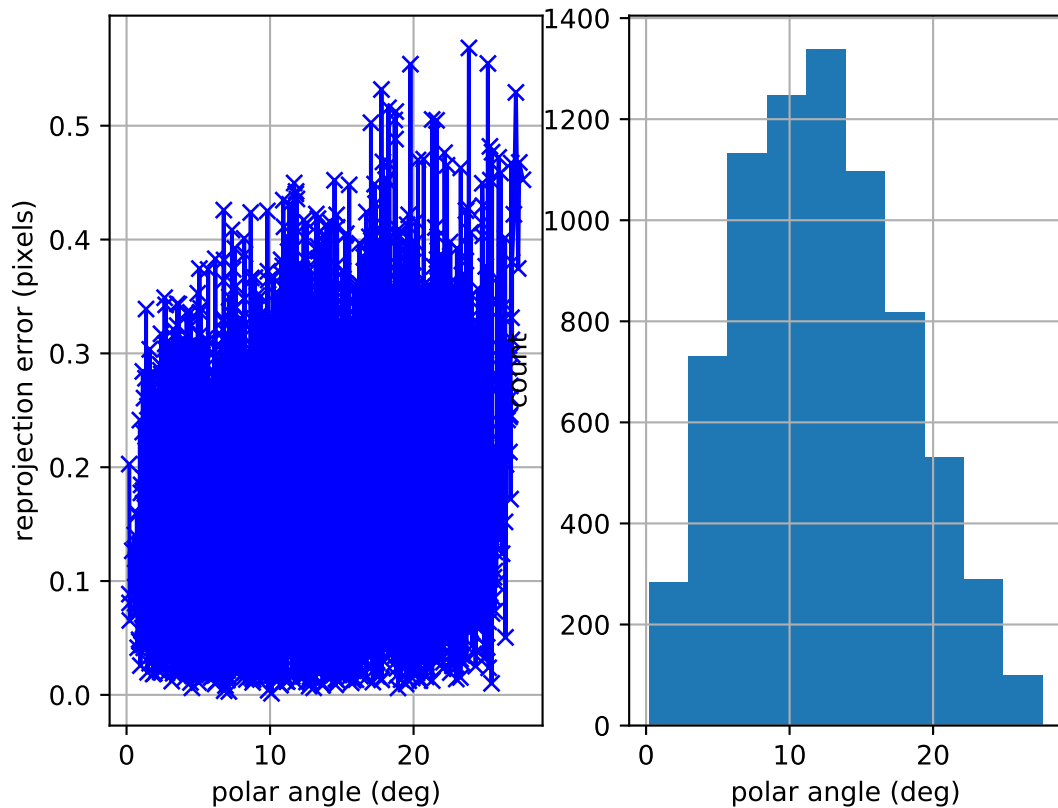Inter-camera observations graph (edge weight=#mutual obs.)
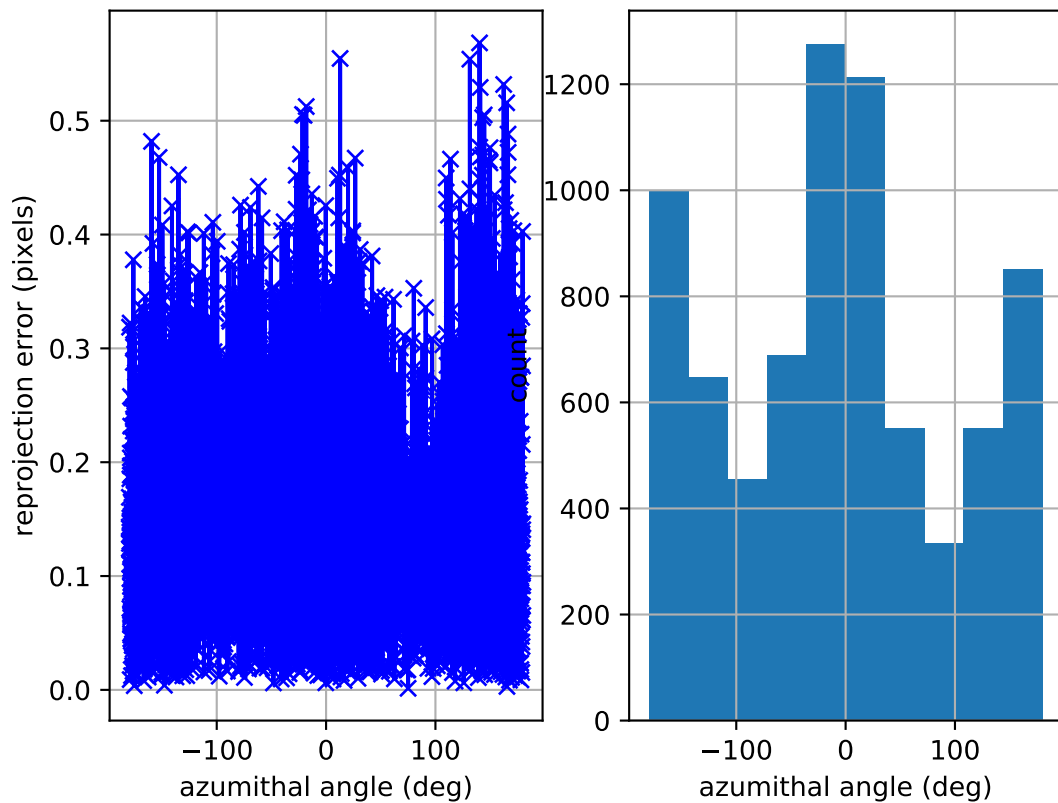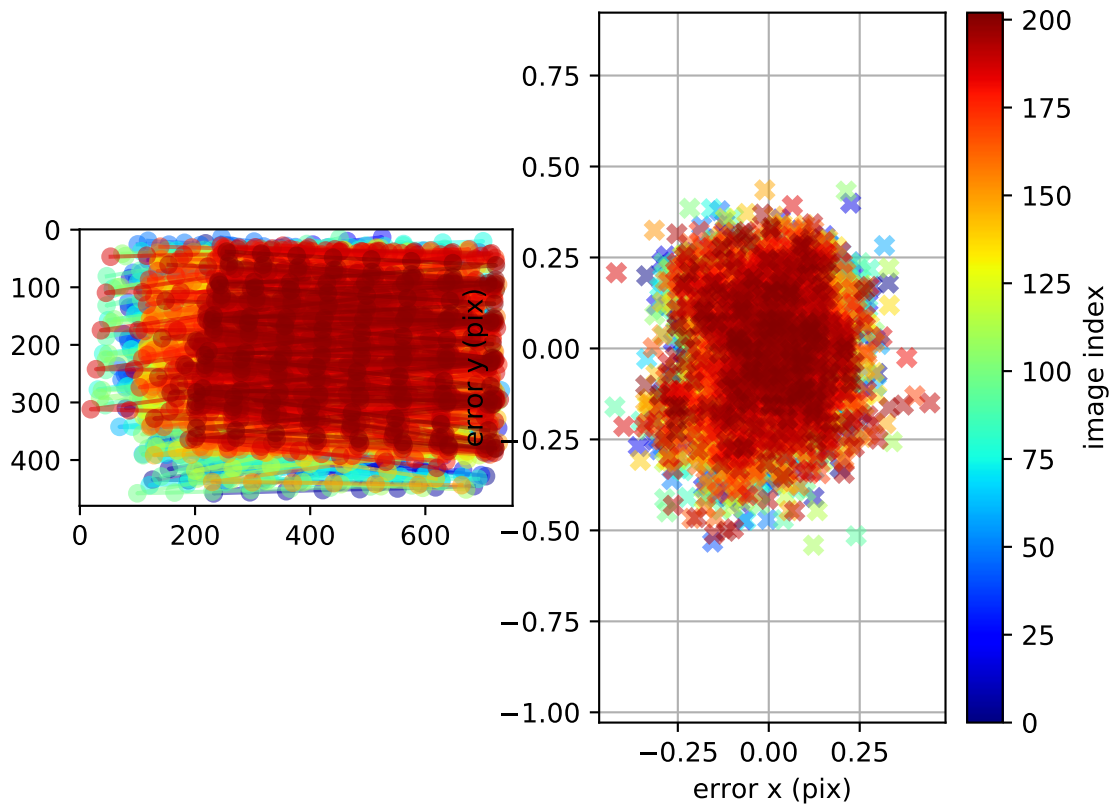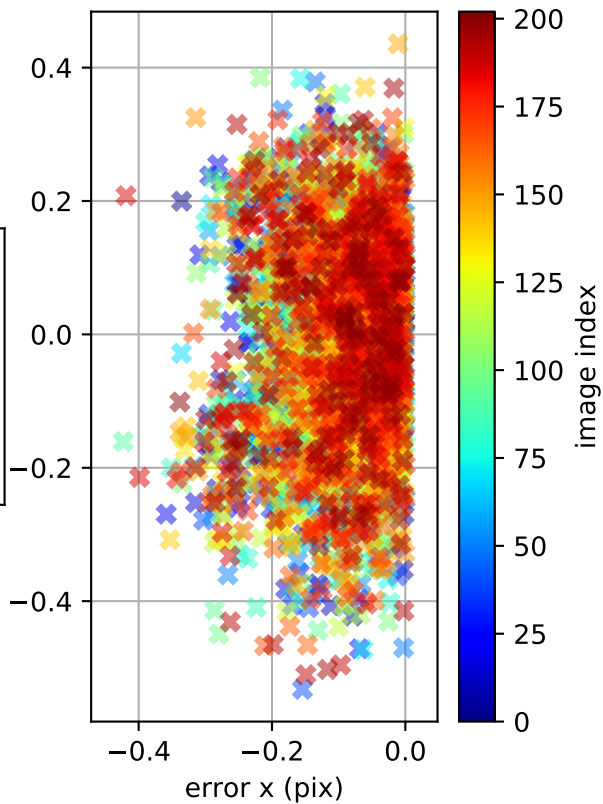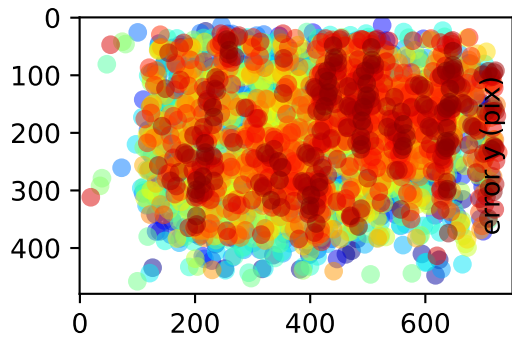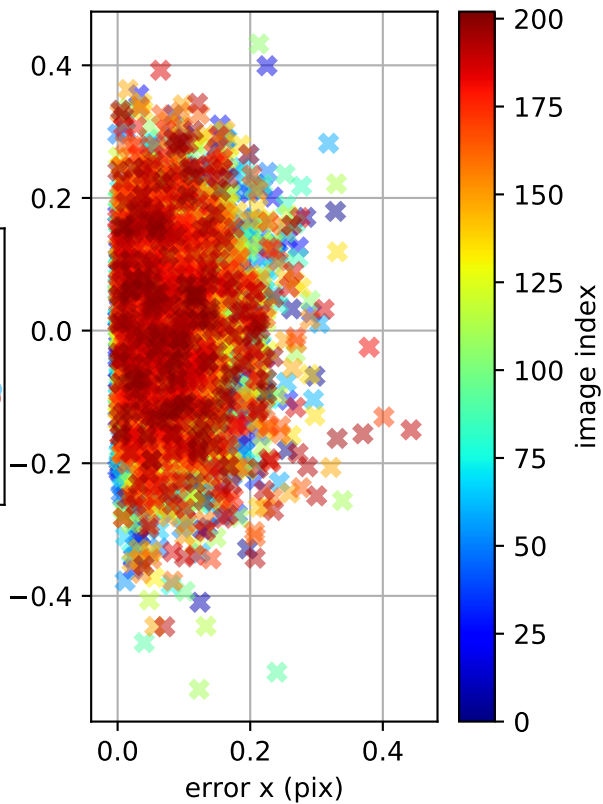
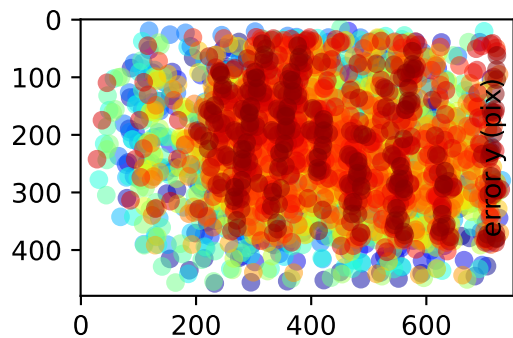camera system

cam0: polar error

cam0: azimutal error

cam0: reprojection errors

cam0: left reprojection errors

cam0: right reprojection errors

cam0: top reprojection errors

cam0: bottom reprojection errors

cam1: polar error

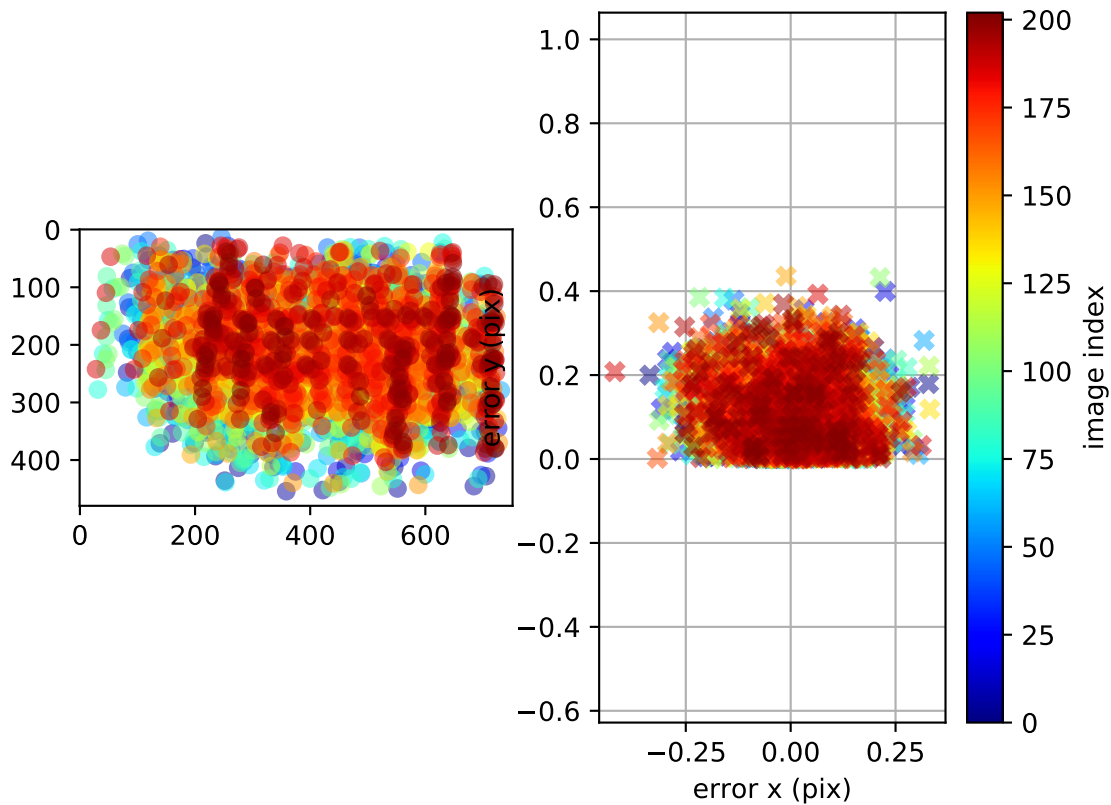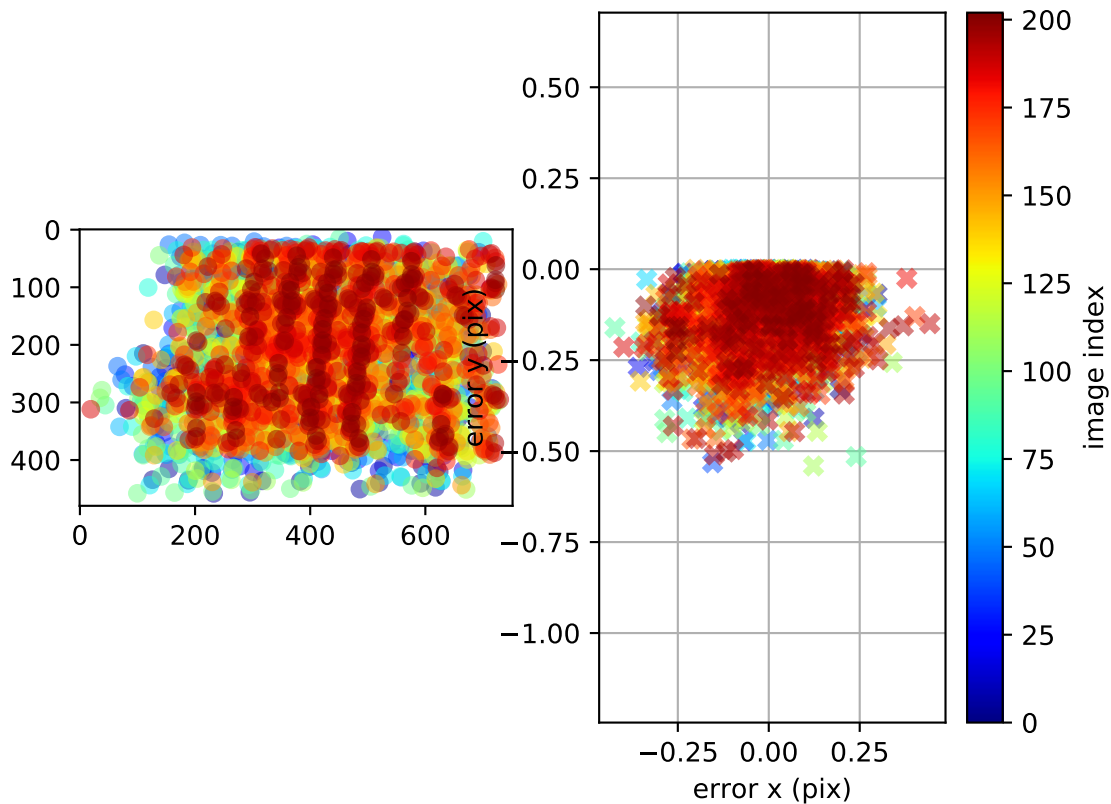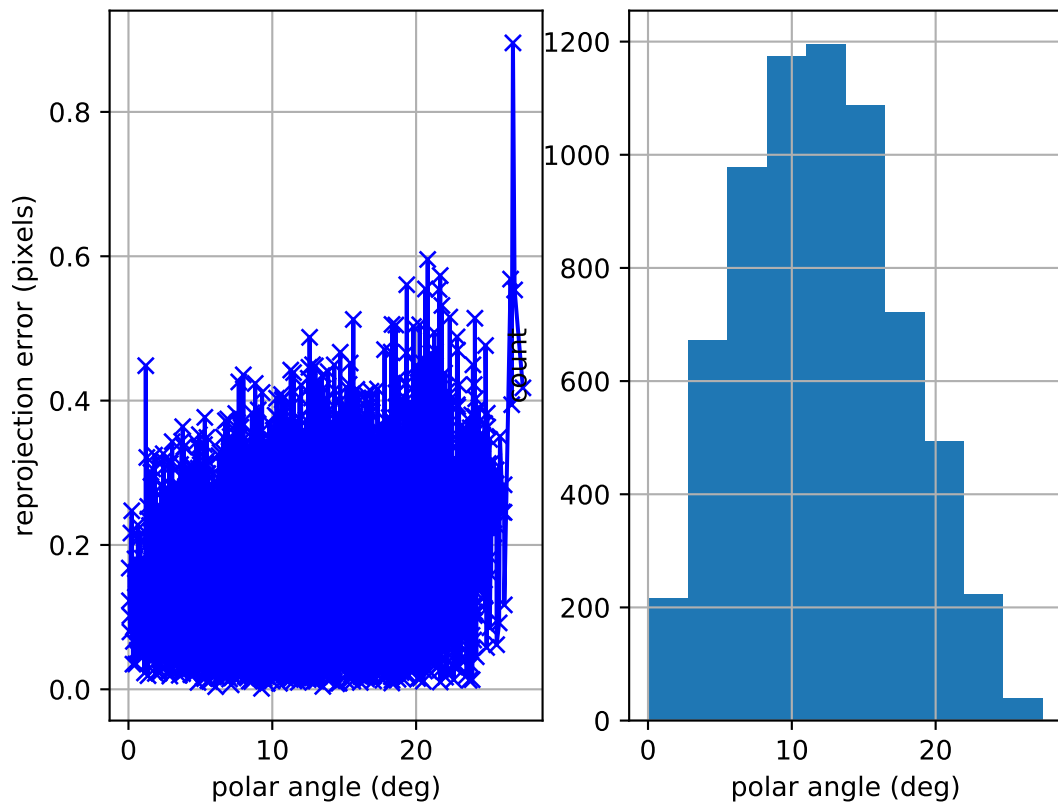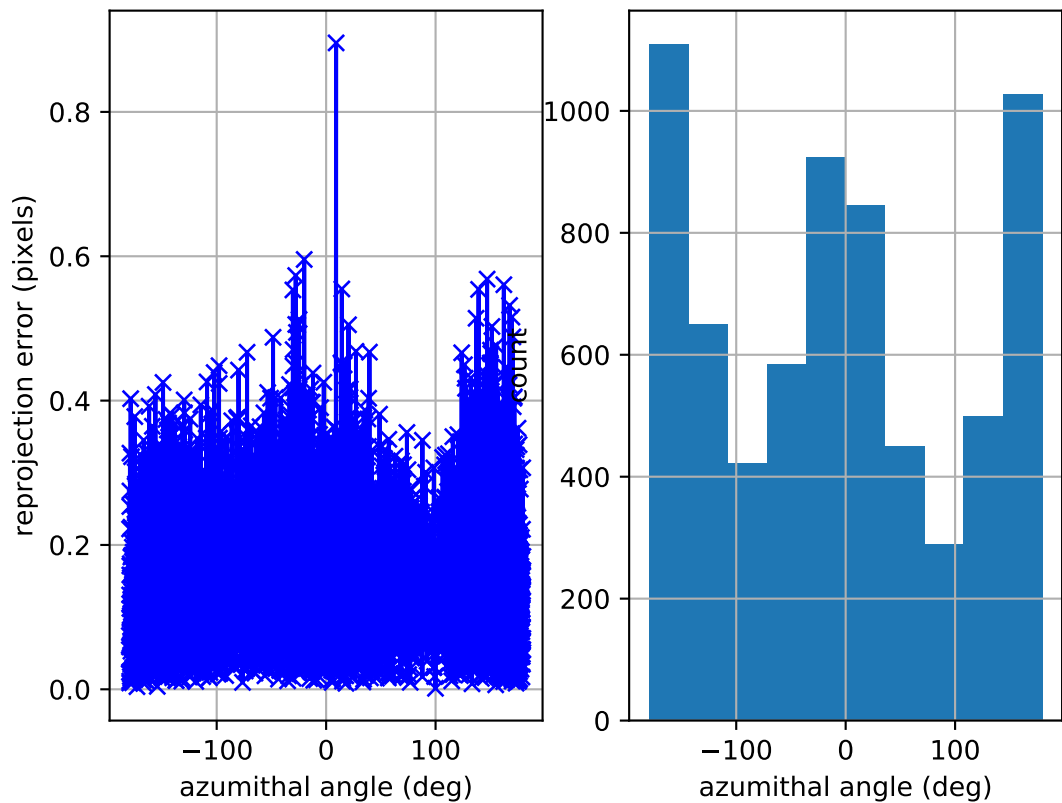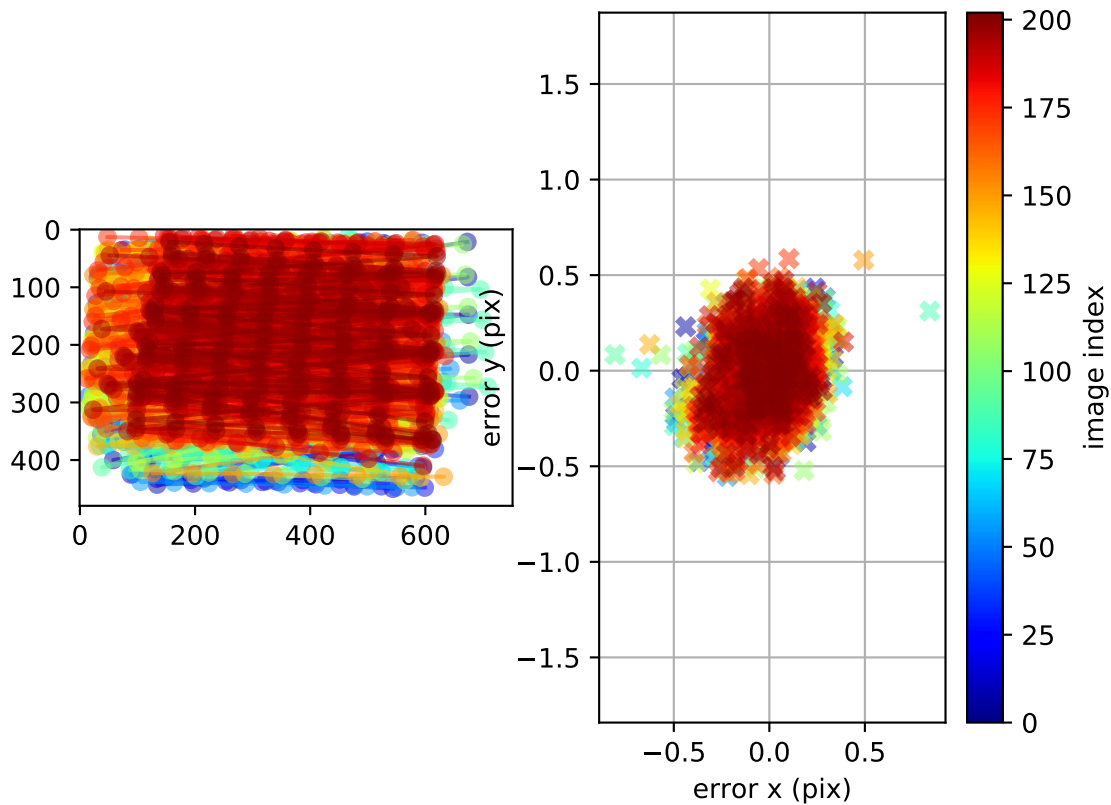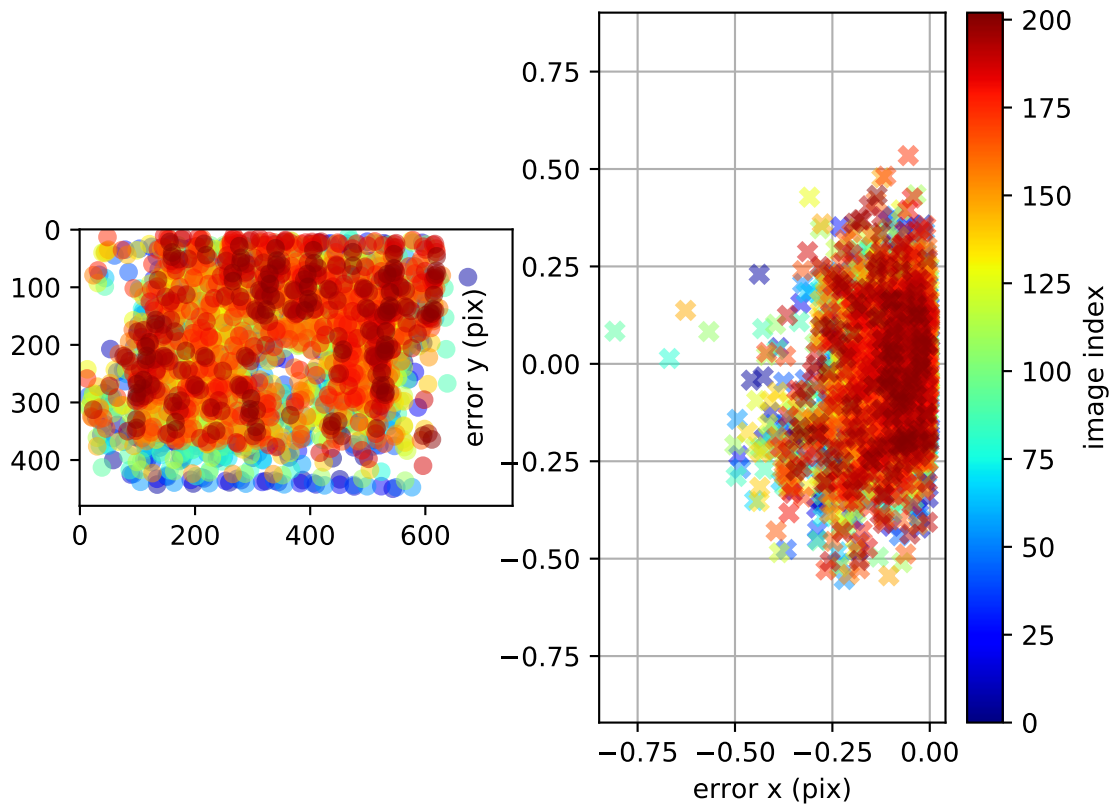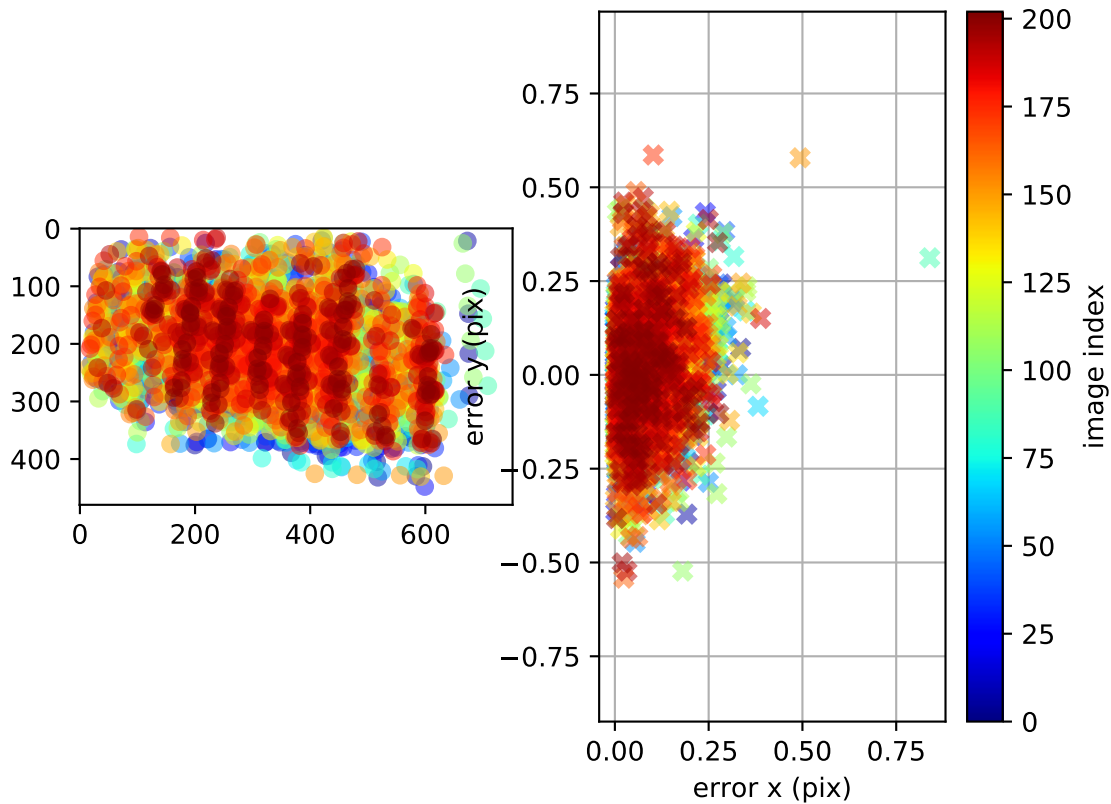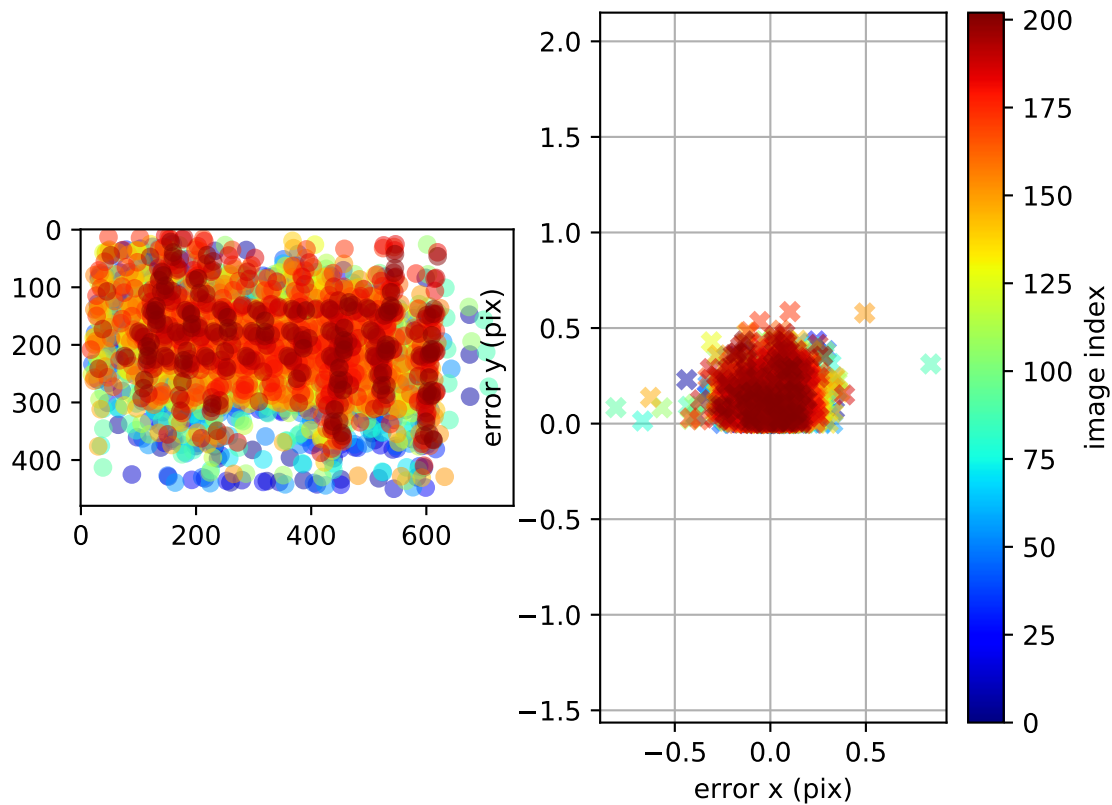cam1: azimutal error

cam1: reprojection errors
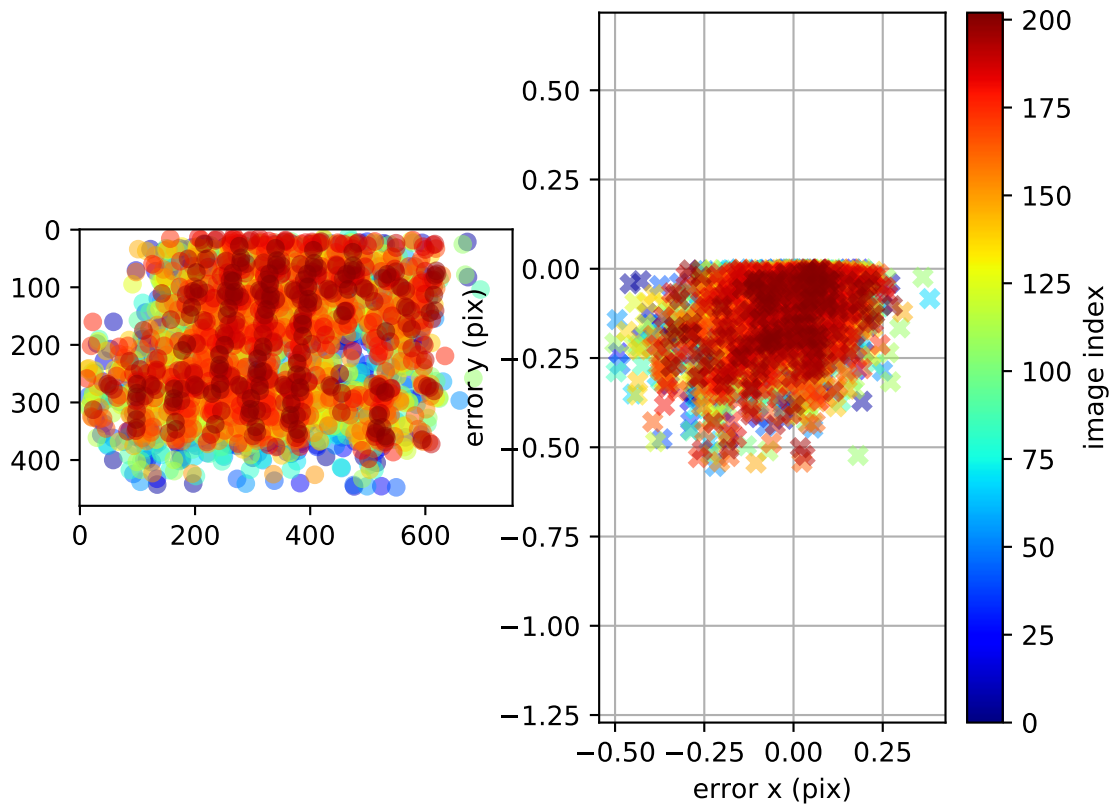
cam1: left reprojection errors
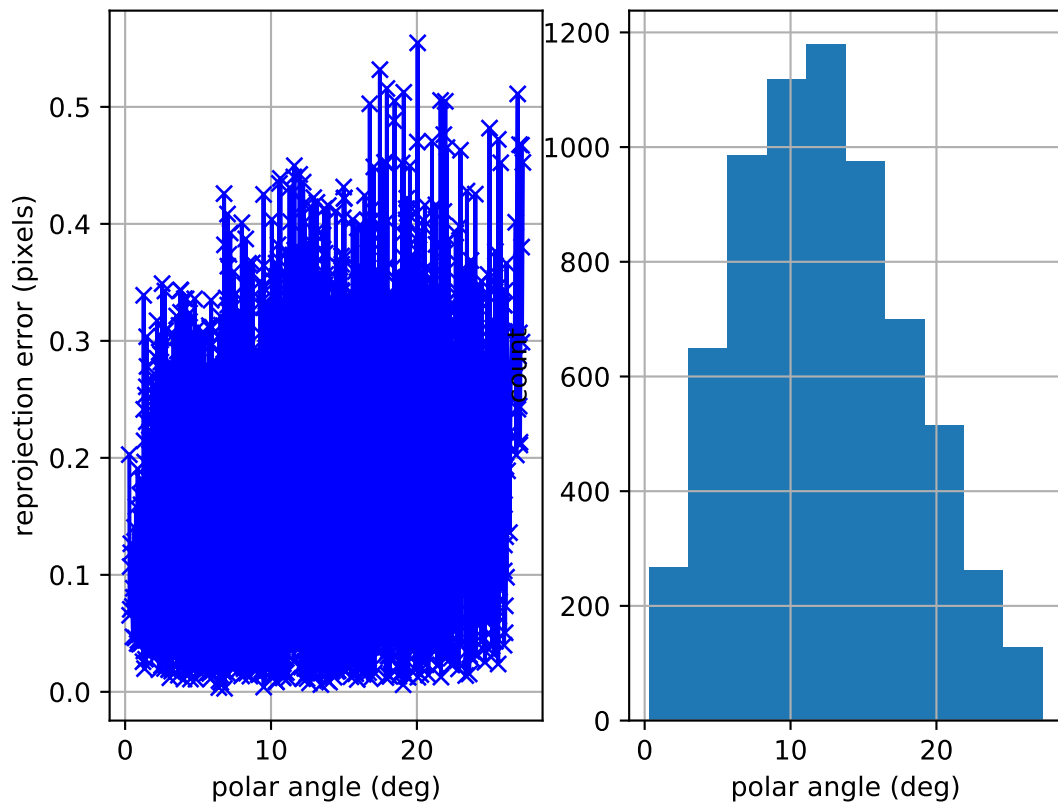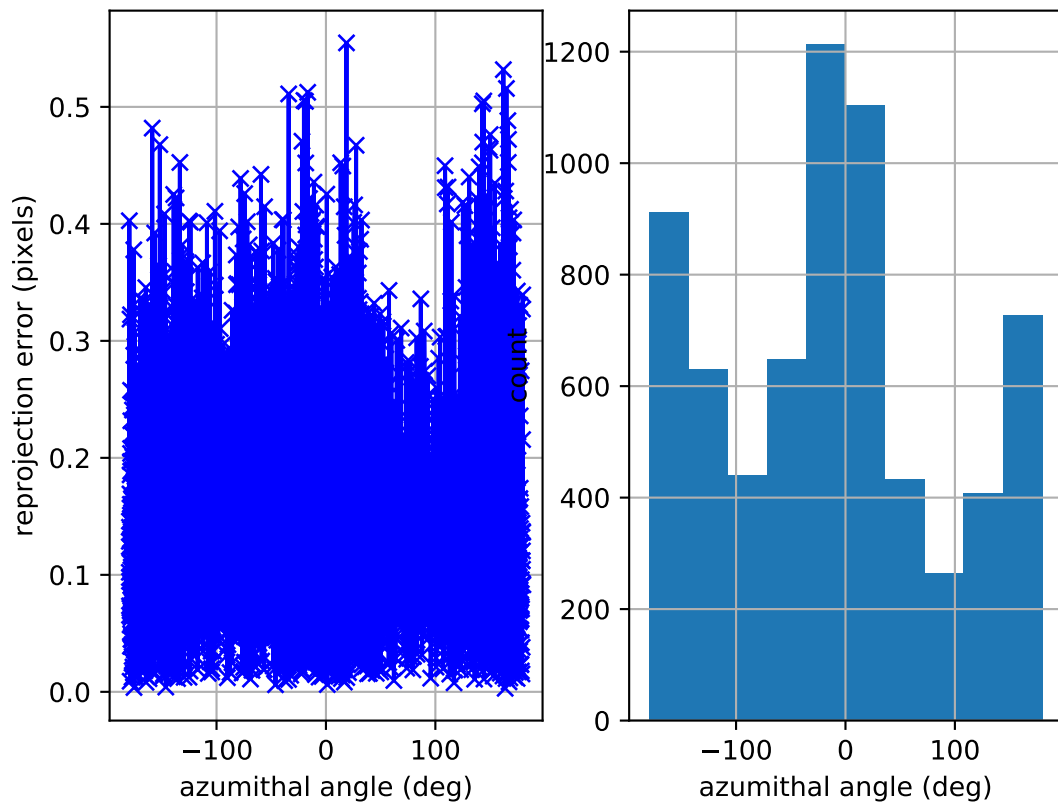
cam1: right reprojection errors
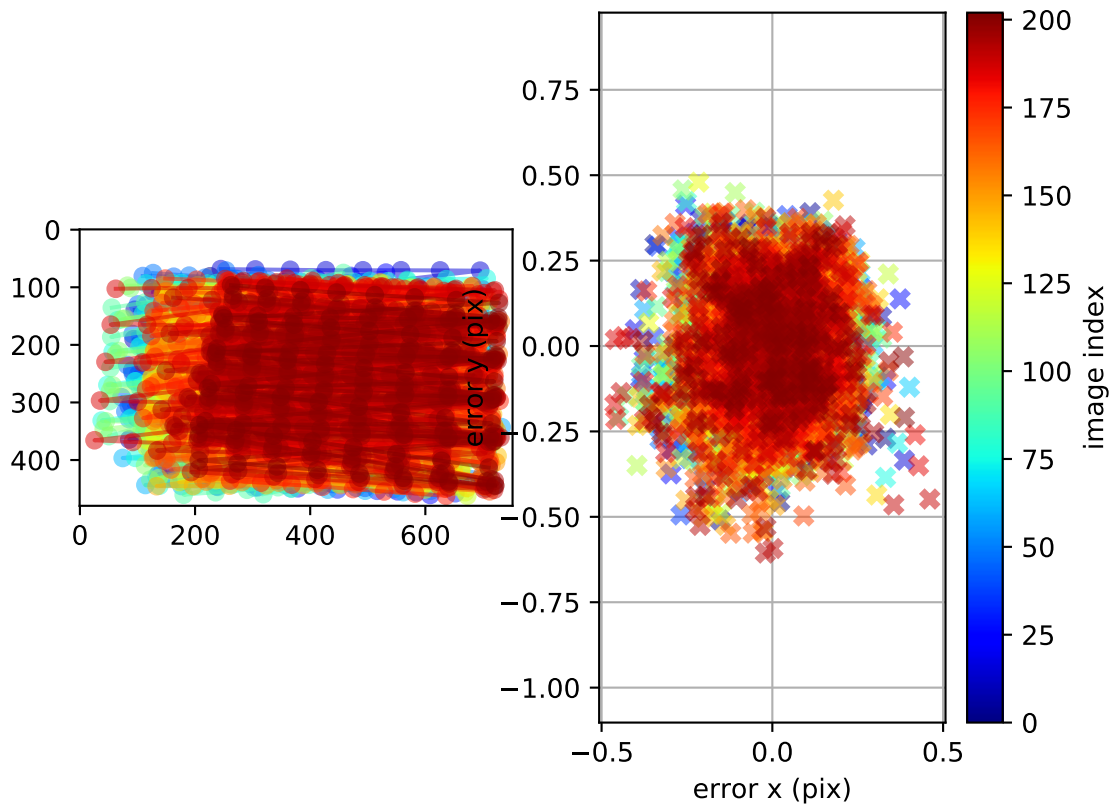
cam1: top reprojection errors
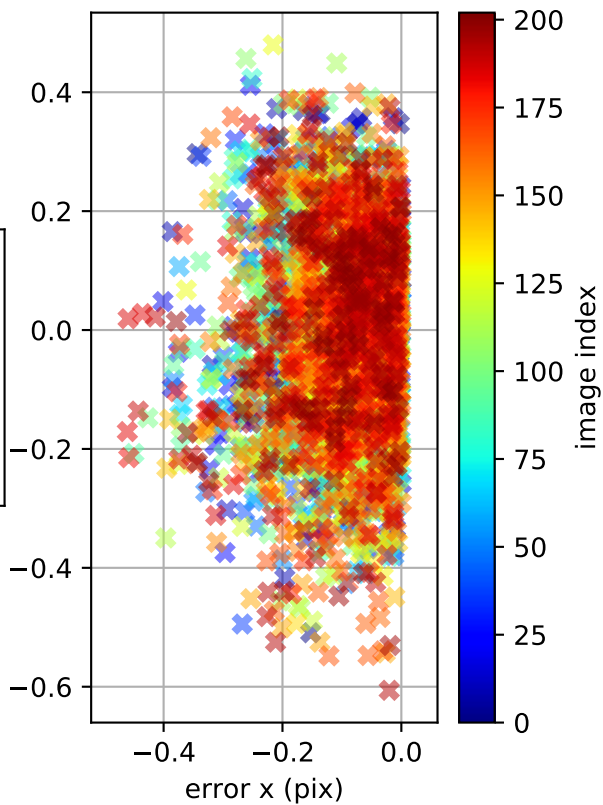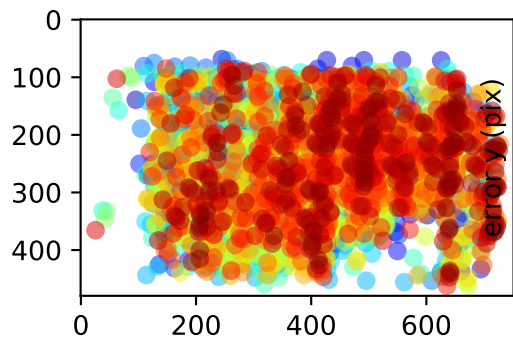
cam1: bottom reprojection errors

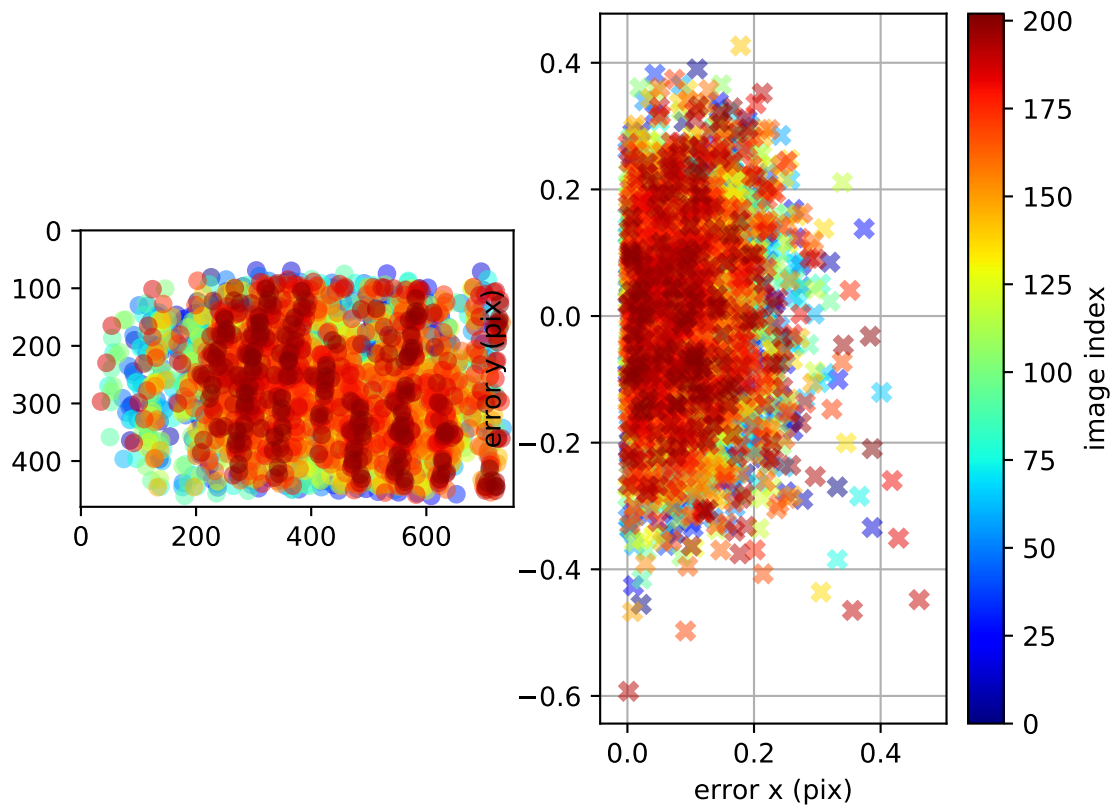cam2: polar error

cam2: azimutal error
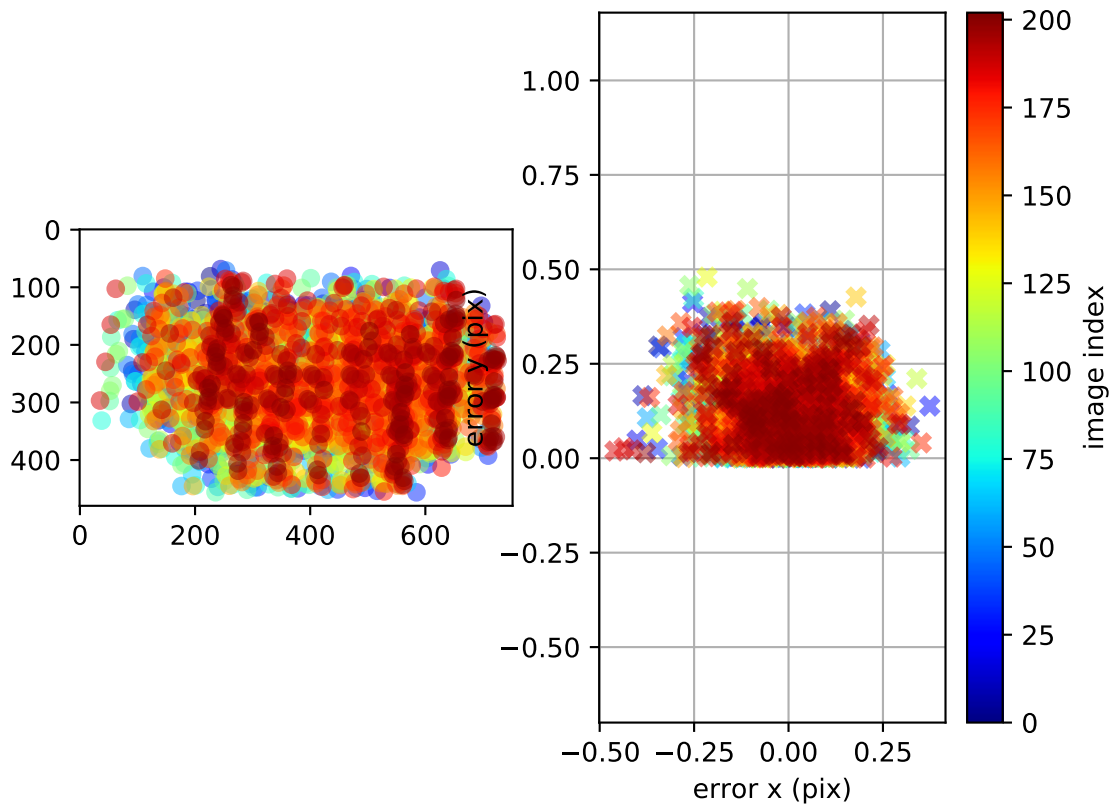
cam2: reprojection errors
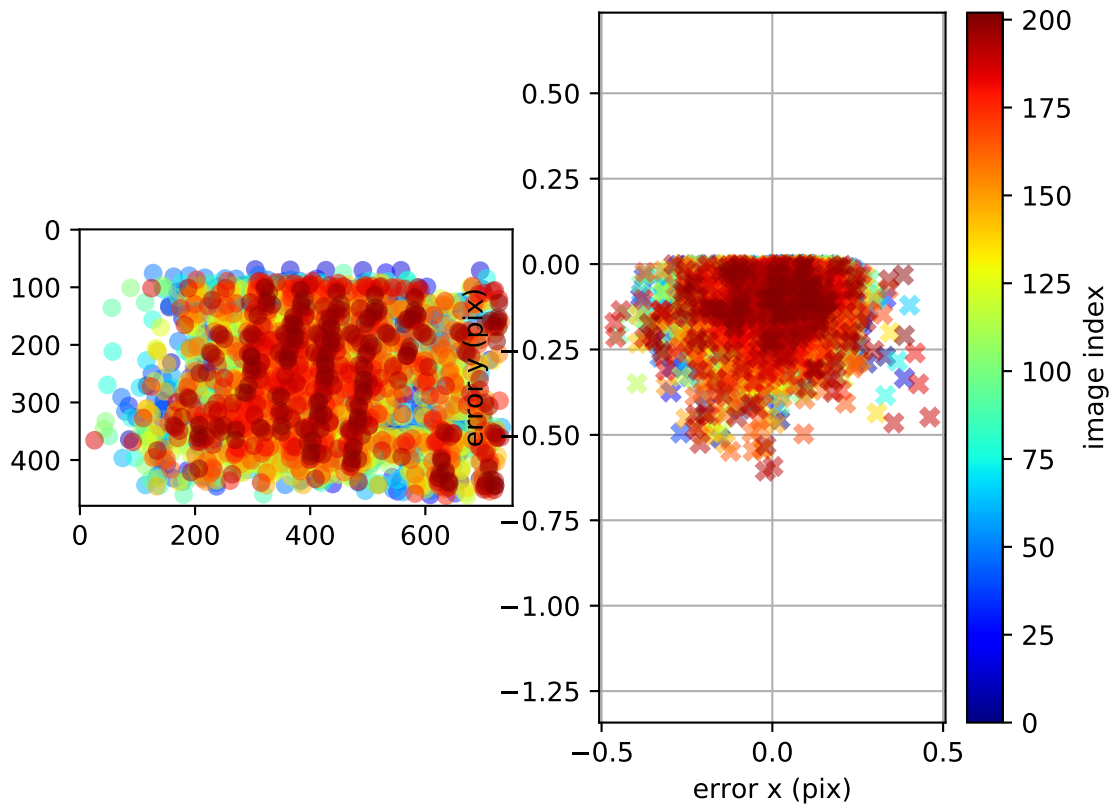
cam2: left reprojection errors
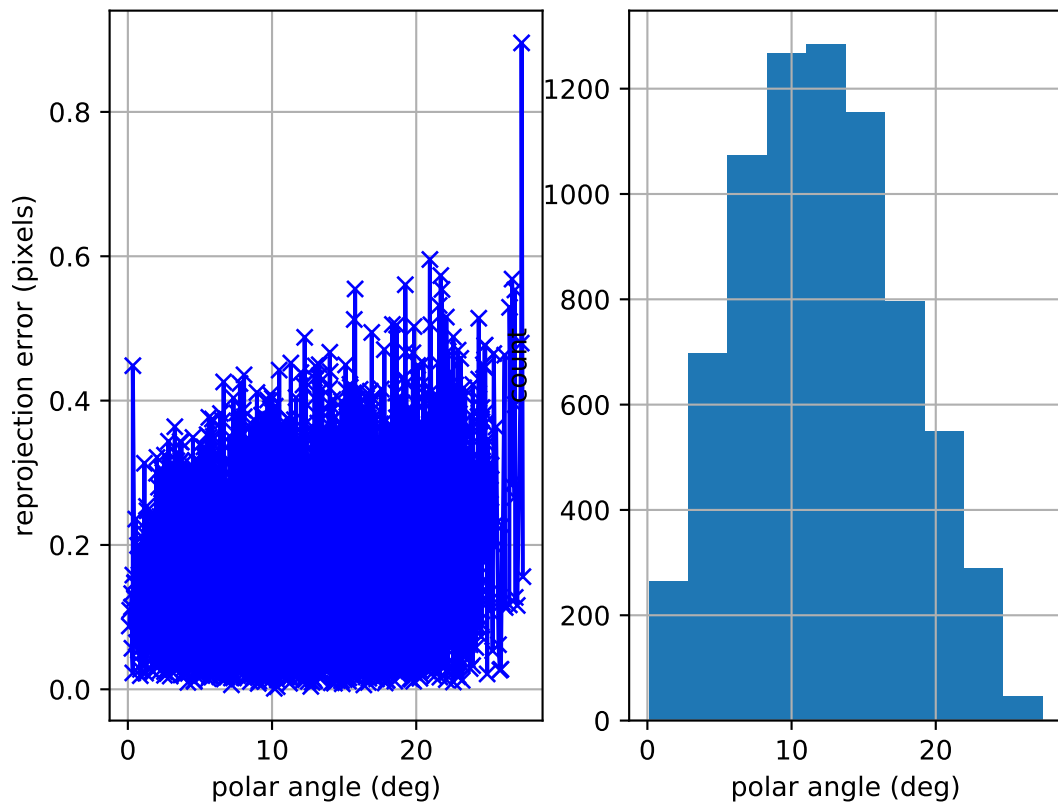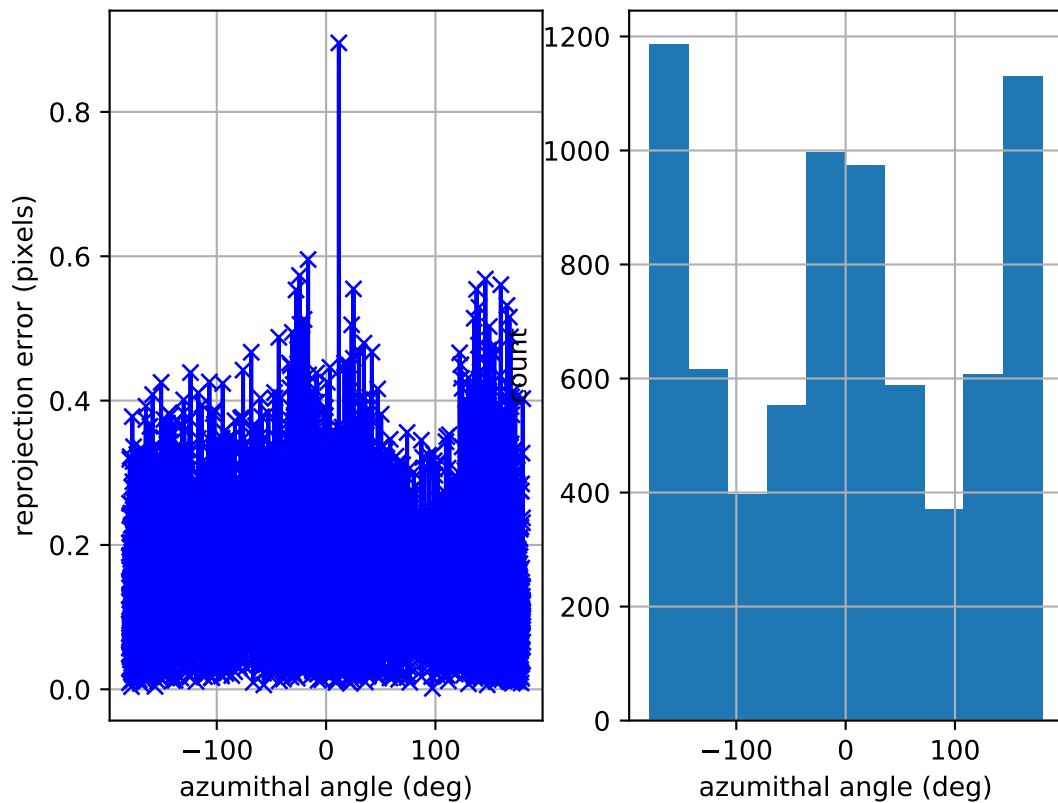
cam2: right reprojection errors
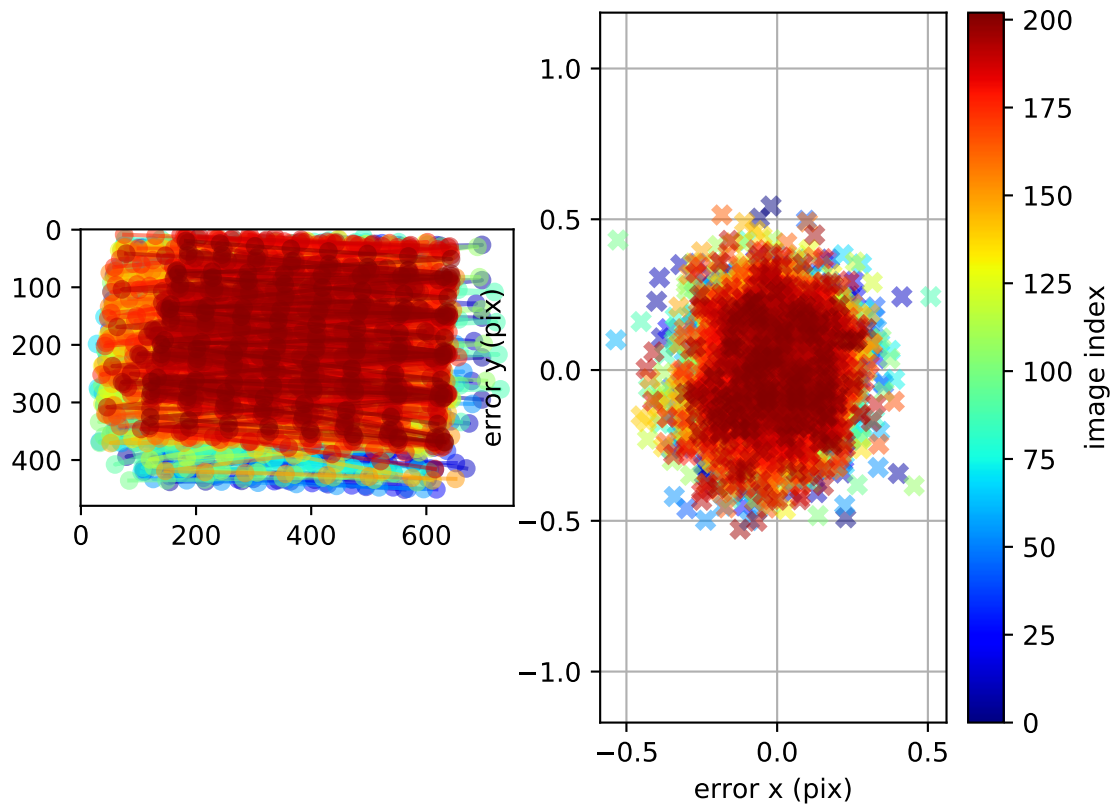
cam2: top reprojection errors

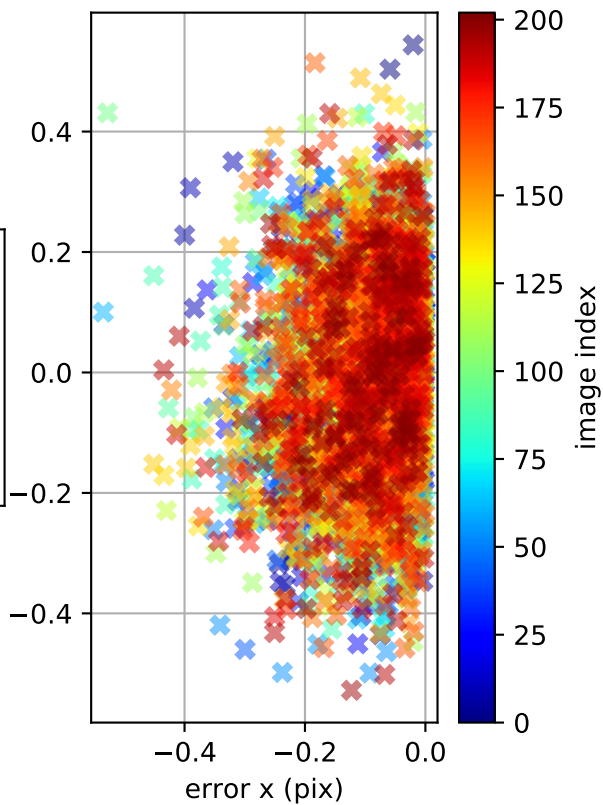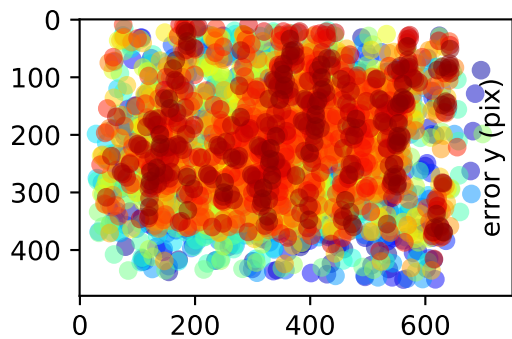cam2: bottom reprojection errors

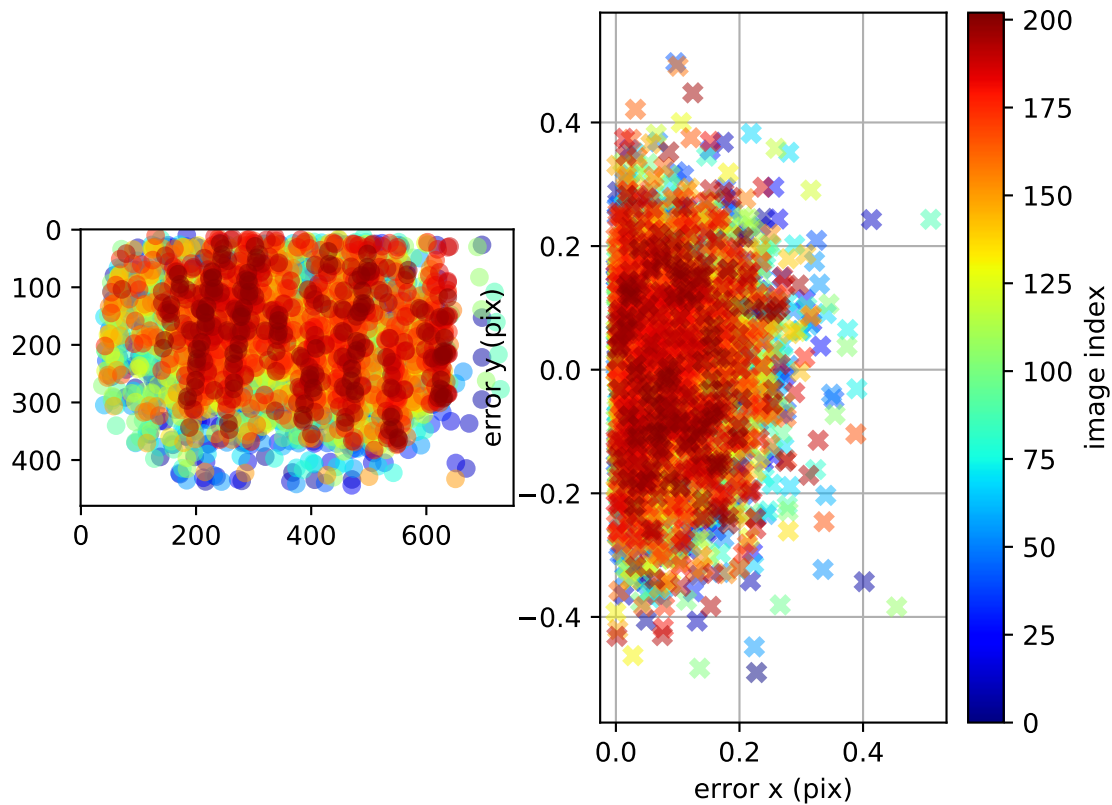cam3: polar error

cam3: azimutal error
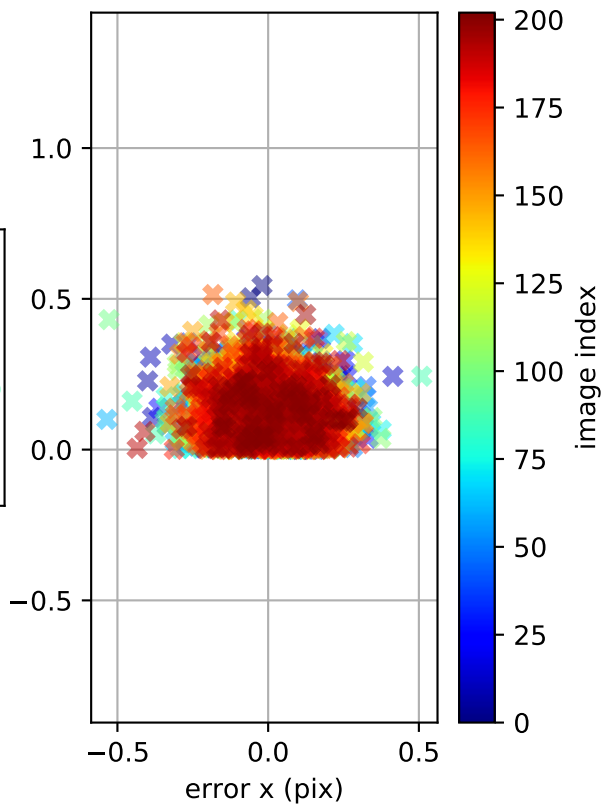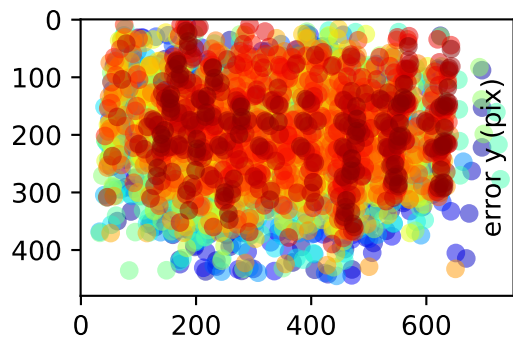
cam3: reprojection errors
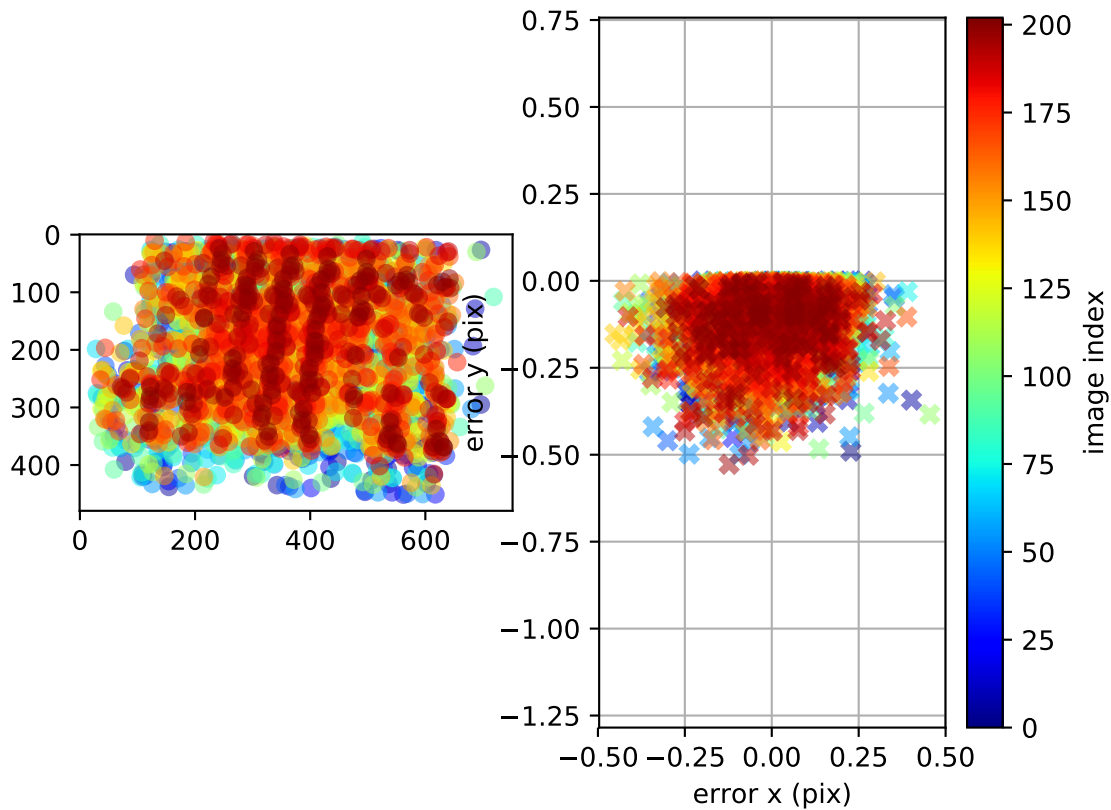
cam3: left reprojection errors

cam3: right reprojection errors

cam3: top reprojection errors

cam3: bottom reprojection errors

Location of removed outlier corners